
Mass of Both Stars in a Simple Binary Star System

Augustin Winther

Department of Physics and Technology (IFT), University of Bergen



Sunday 27th November, 2022

Abstract — This paper uses the center of mass equation, Newton's law of gravitation, and the formula for centripetal acceleration to derive equations for the individual masses of the two stars in a binary star system; assuming constant non-relativistic orbital speeds and circular orbits on the same plane.

Center of mass equation:

$$m_1 r_1 = m_2 r_2 \quad (1)$$

Given a circular orbit with constant orbital speed v , and an orbital period T , we have:

$$v = \frac{2\pi r}{T} \implies r = \frac{vT}{2\pi} \quad (2)$$

From the equations (1) and (2), we can derive the following:

$$\begin{aligned} m_1 r_1 &= m_2 r_2 \\ \implies \frac{r_1}{r_2} &= \frac{m_2}{m_1} \\ \stackrel{(2)}{\implies} \frac{\frac{v_1 T}{2\pi}}{\frac{v_2 T}{2\pi}} &= \frac{m_2}{m_1} \\ \implies \frac{v_1}{v_2} &= \frac{m_2}{m_1} \end{aligned} \quad (3)$$

Let there be a constant b , representing the equal ratios from equations (1) and (3):

$$b = \frac{r_1}{r_2} = \frac{v_1}{v_2} = \frac{m_2}{m_1} \quad (4)$$

From equation (4), we note the following:

$$\begin{aligned} r_2 &= \frac{r_1}{b} \\ v_2 &= \frac{v_1}{b} \end{aligned}$$

We also note that the distance between the two masses can be written as:

$$r = r_1 + r_2 \stackrel{(4)}{=} r_1 + \frac{r_1}{b} = r_1 \left(1 + \frac{1}{b}\right) \quad (5)$$

Using Newton's law of gravitation and the formula for centripetal acceleration, we derive the following:

$$\begin{aligned} m_2 a_2 &= G \frac{m_1 m_2}{r^2} \\ \implies a_2 &= G \frac{m_1}{r^2} \\ \implies \frac{v_2^2}{r_2} &= G \frac{m_1}{r^2} \\ \stackrel{(4)}{\implies} \frac{\left(\frac{v_1}{b}\right)^2}{r_2} &= G \frac{m_1}{r^2} \\ \implies \frac{v_1^2}{r_1 b} &= G \frac{m_1}{r^2} \\ \stackrel{(5)}{\implies} \frac{v_1^2}{r_1 b} &= G \frac{m_1}{r_1^2 \left(1 + \frac{1}{b}\right)^2} \\ \implies m_1 &= \frac{v_1^2 r_1^2 \left(1 + \frac{1}{b}\right)^2}{r_1 G b} \\ \implies m_1 &= \frac{v_1^2 r_1 \left(1 + \frac{1}{b}\right)^2}{G b} \\ \stackrel{(2)}{\implies} m_1 &= \frac{v_1^2 \frac{v_1 T}{2\pi} \left(1 + \frac{1}{b}\right)^2}{G b} \\ \implies m_1 &= \frac{v_1^3 T \left(1 + \frac{1}{b}\right)^2}{2\pi G b} \\ \implies m_1 &= \frac{\left(\frac{2\pi r_1}{T}\right)^3 T \left(1 + \frac{1}{b}\right)^2}{2\pi G b} \\ \implies m_1 &= \frac{8\pi^3 r_1^3 T \left(1 + \frac{1}{b}\right)^2}{2\pi T^3 G b} \\ \implies m_1 &= \frac{4\pi^2 r_1^3 \left(1 + \frac{1}{b}\right)^2}{T^2 G b} \\ \implies m_1 &= \frac{4\pi^2 r_1^3 \left(1 + \frac{1}{b}\right)^2}{T^2 G b} \end{aligned}$$

m_2 can be derived from m_1 and equation (4):

$$m_2 = m_1 \frac{m_2}{m_1} \stackrel{(4)}{=} m_1 b = \frac{4\pi^2 r_1^3}{T^2 G} \left(1 + \frac{1}{b}\right)^2$$